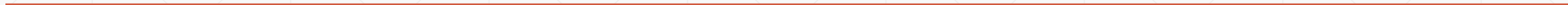


Discriminating Underwater LiDAR Target Signatures using Sparse Multi-spectral Depth Codes

Puneet Chhabra, PhD Candidate (2017)

Aurora Maccarone, Aongus McCarthy, Andrew M Wallace and Gerald S Buller

Supervisors: Andrew M Wallace, James R Hopgood

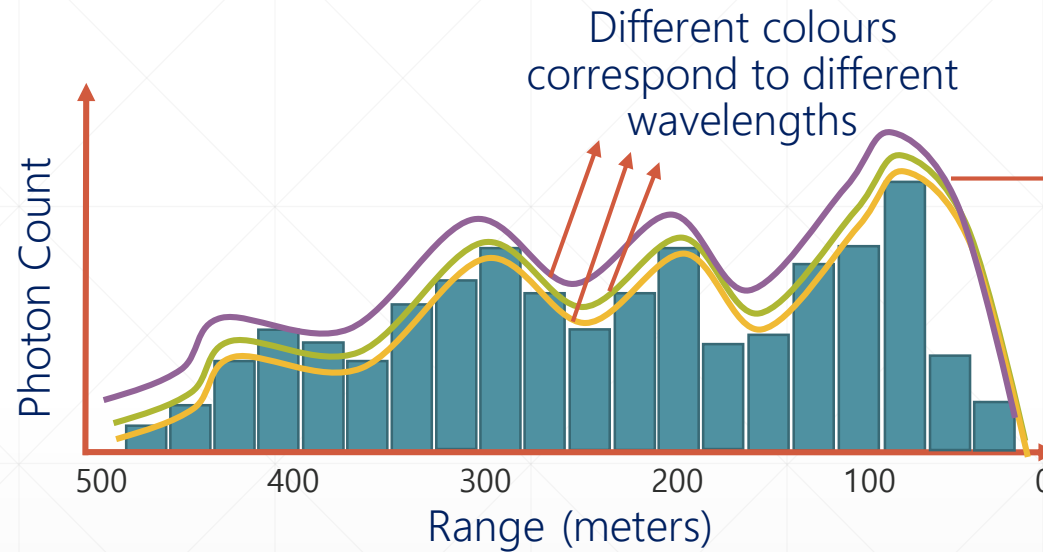
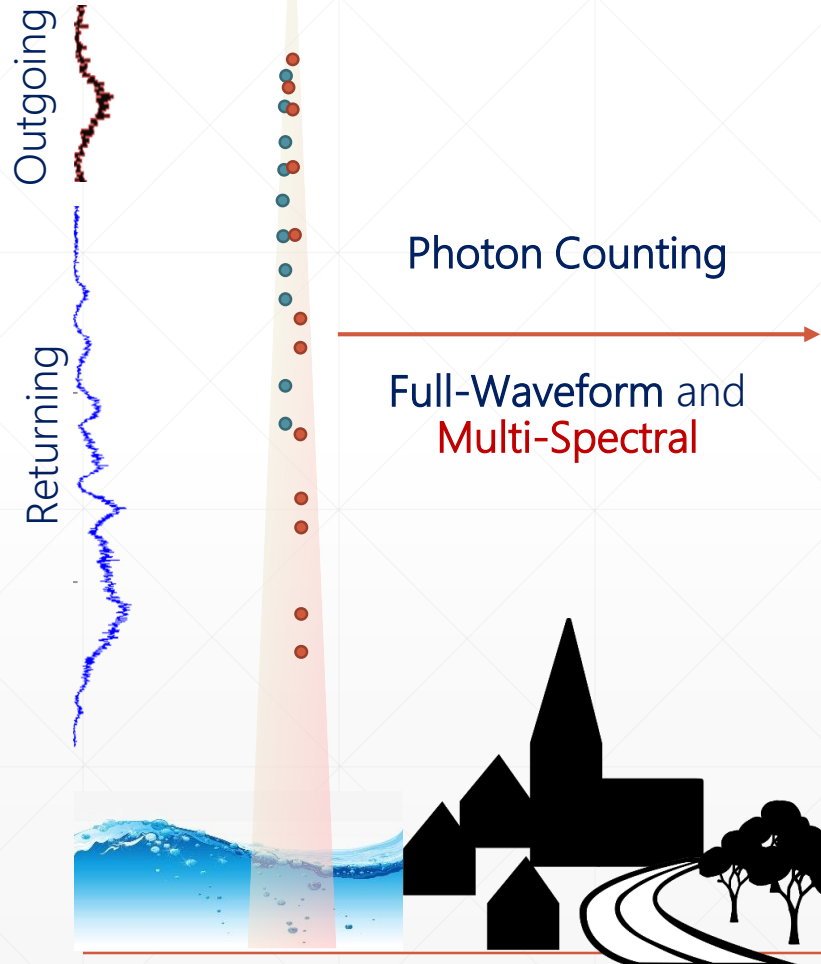


“Aim: Analyse **Full-Waveform Multi-Spectral Single Photon Counting (SPC) LiDAR** data in order to improve aerial and bathymetric situational awareness”.

“First piece of work to show that underwater LiDAR can be an alternative to sonar based mine-countermeasures...”



“Aim: Analyse **Full-Waveform Multi-Spectral Single Photon Counting (SPC) LiDAR** data in order to improve aerial and bathymetric situational awareness”.

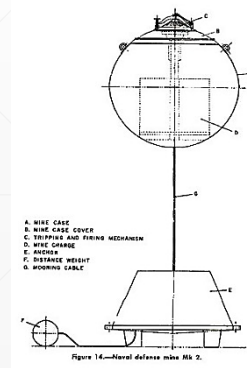


Combined with a scanning system full-waveforms lead to a 3D point cloud

Underwater Mine Countermeasures

Aims

- Classify target (mine) signatures...
using FW multi-spectral LiDAR
- Combining material classification
plastics, concrete, metal
- Potentially hidden behind foliage
plants or other materials

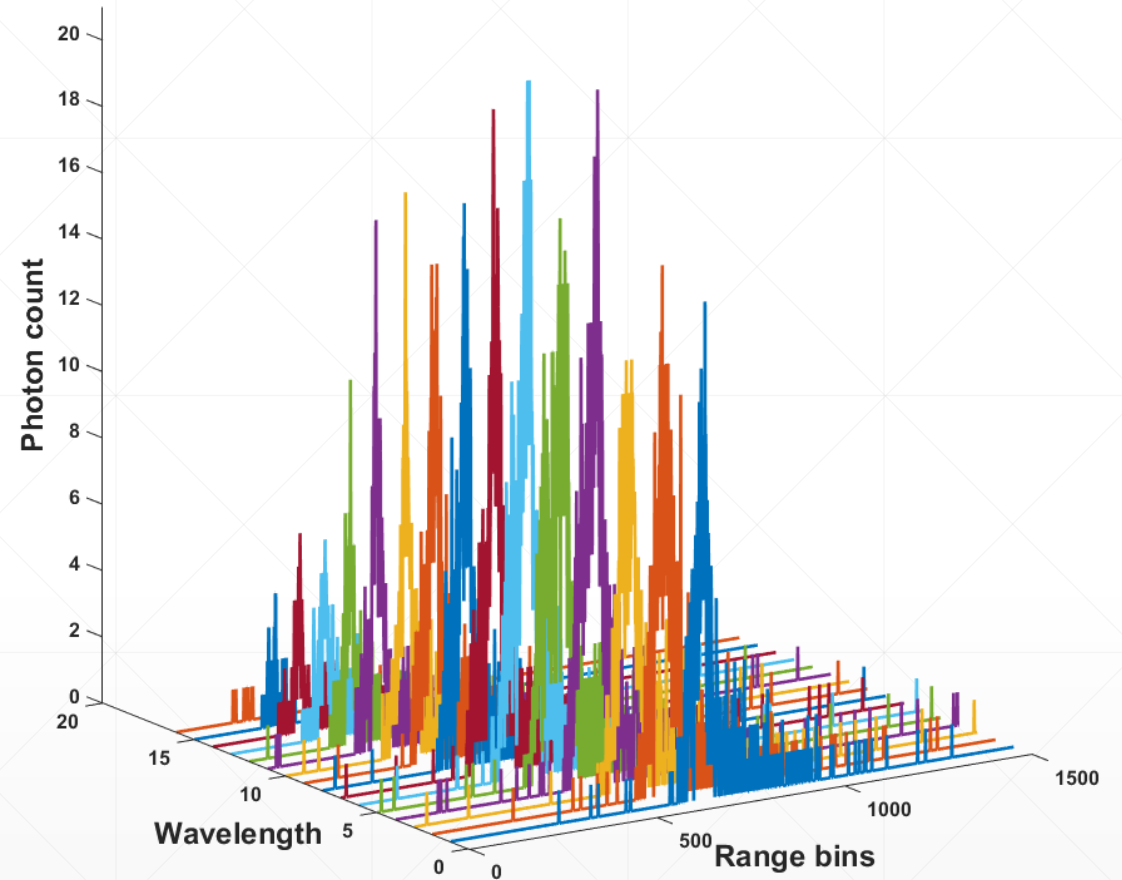


1917- 1919 Mine Dump at Inverness*, Scotland

* <http://www.worldwar1.com/dbc/nsminebr.htm>

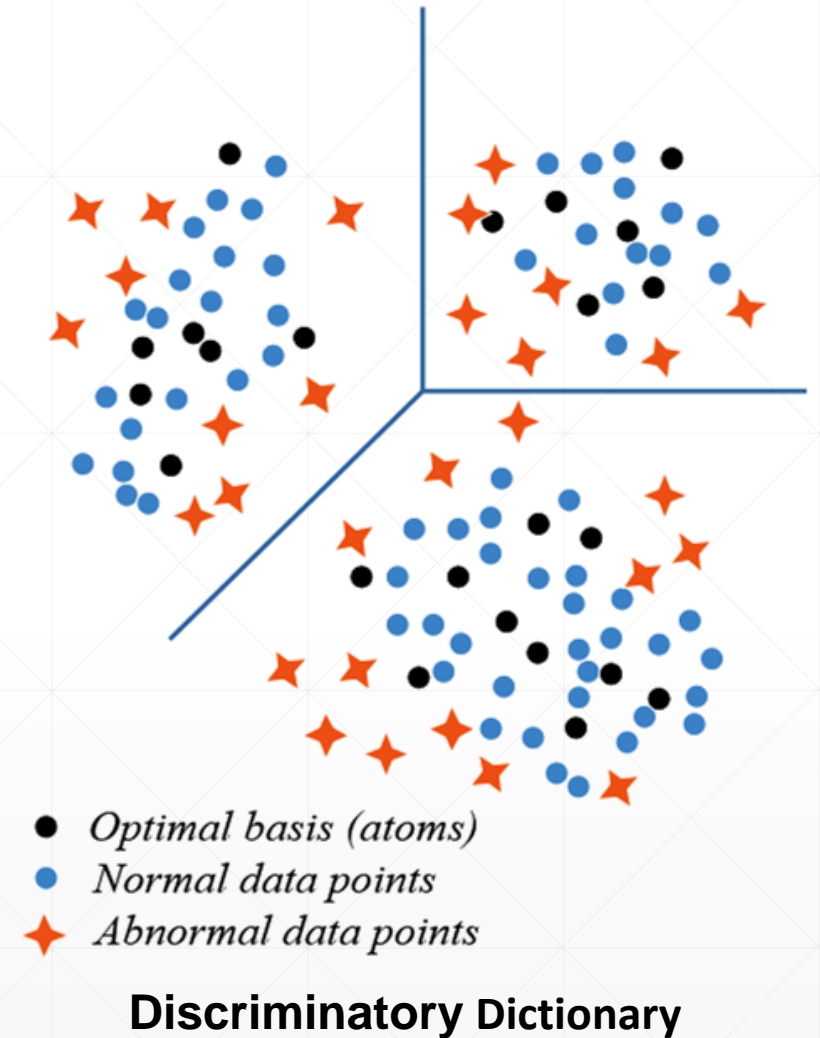
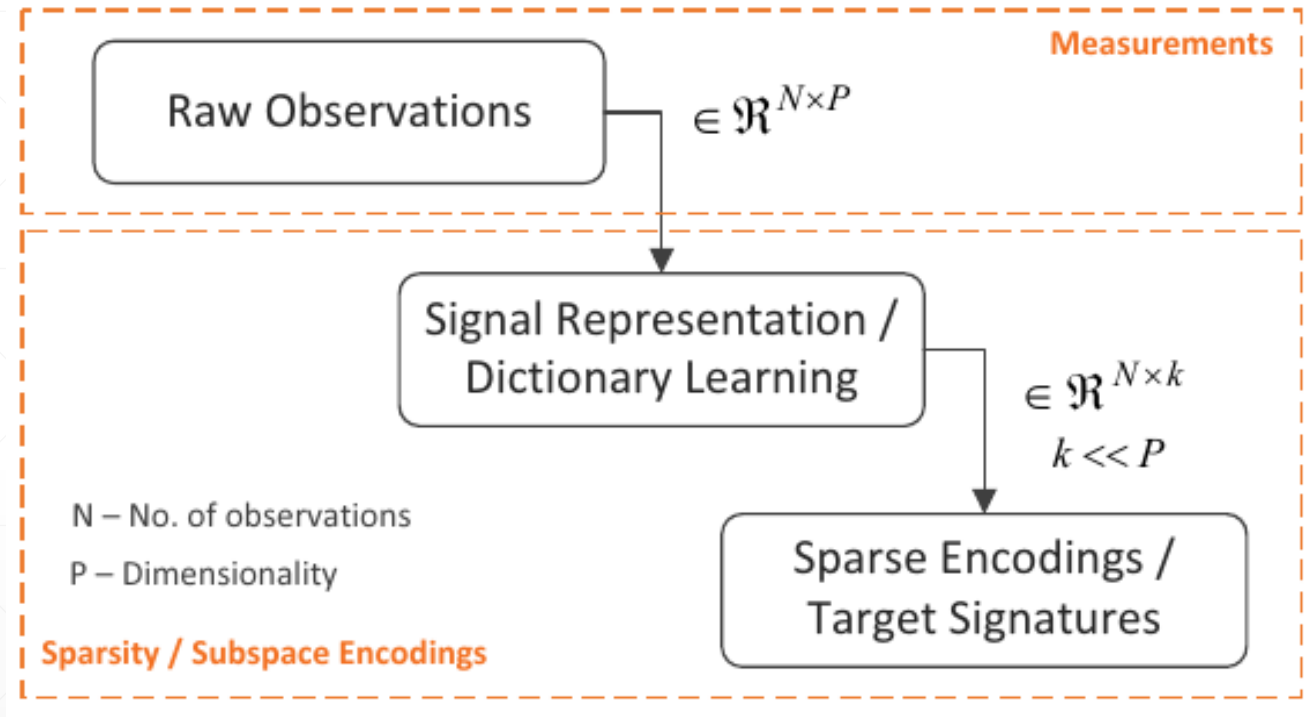
Outline

- **Problem Overview**
- **SPC Experimental Setup**
- **Methodology**
- **Results**
- **Future work & Improvements**

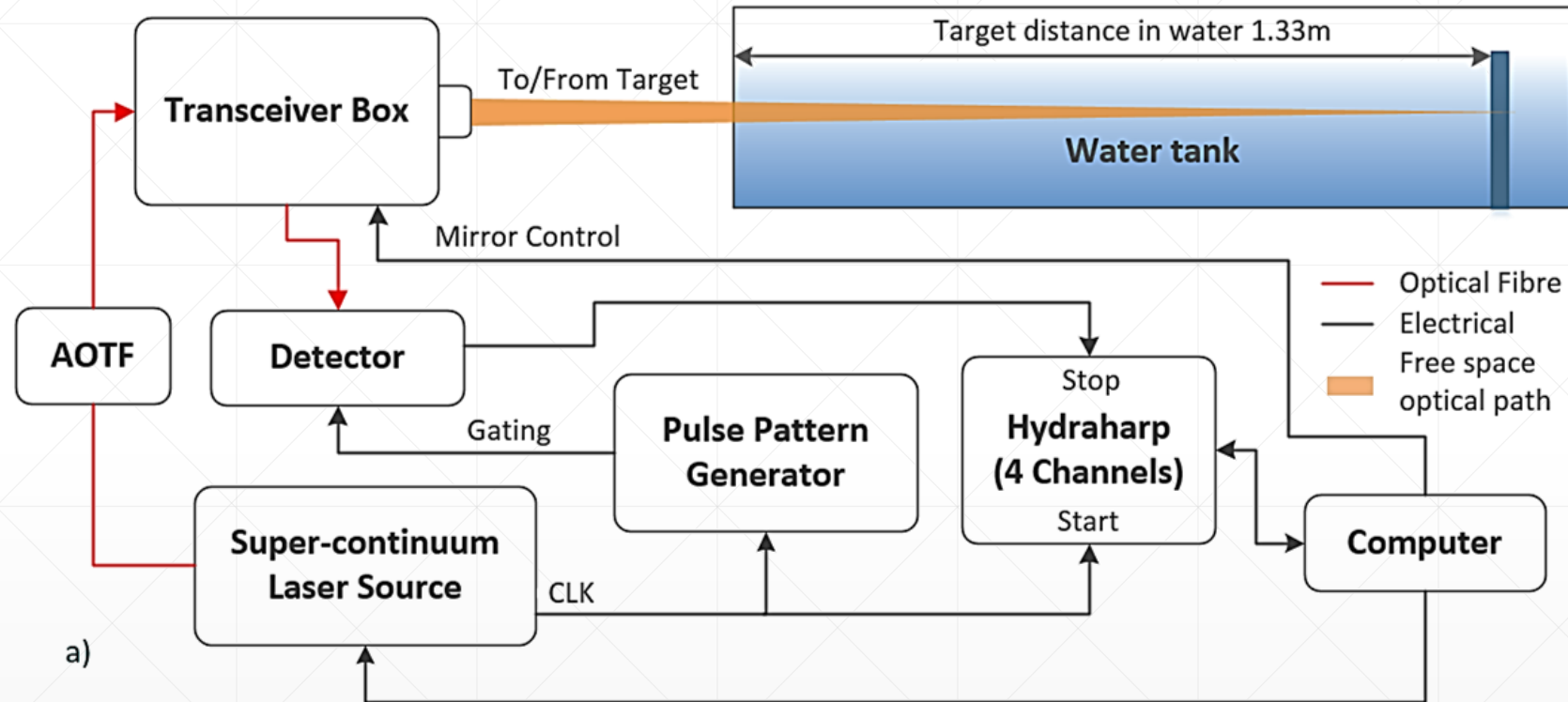


Multi-Spectral Single Photon Counting Waveforms

Problem Overview

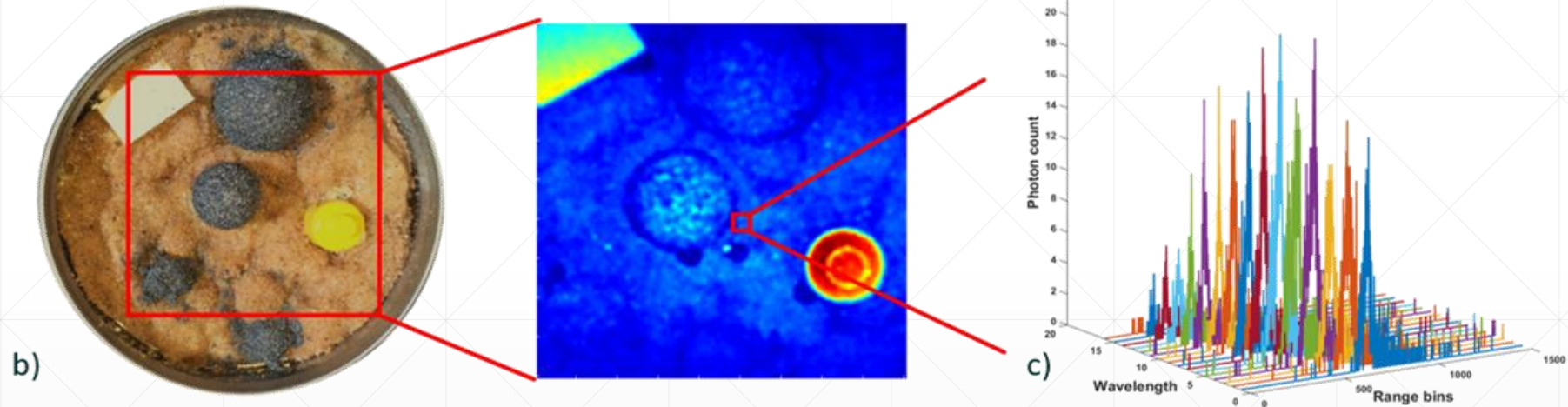


SPC Experimental Setup



A. Maccarone, A. McCarthy, X. Ren, R. E. Warburton, A. M. Wallace, J. Moffat, Y. Petillot, and G. S. Buller, "Underwater depth imaging using time-correlated single photon counting," *Optics Express*, vol. 23, no. 26, pp. 33911–33926, 2015.

SPC Experimental Setup



Target Under Investigation



Materials used



Sand



Waterproof glue



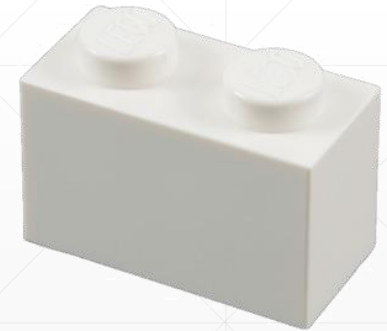
Texture Paint



Metal ball bearings



Lego blocks



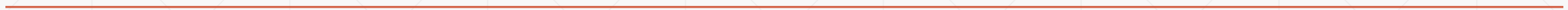
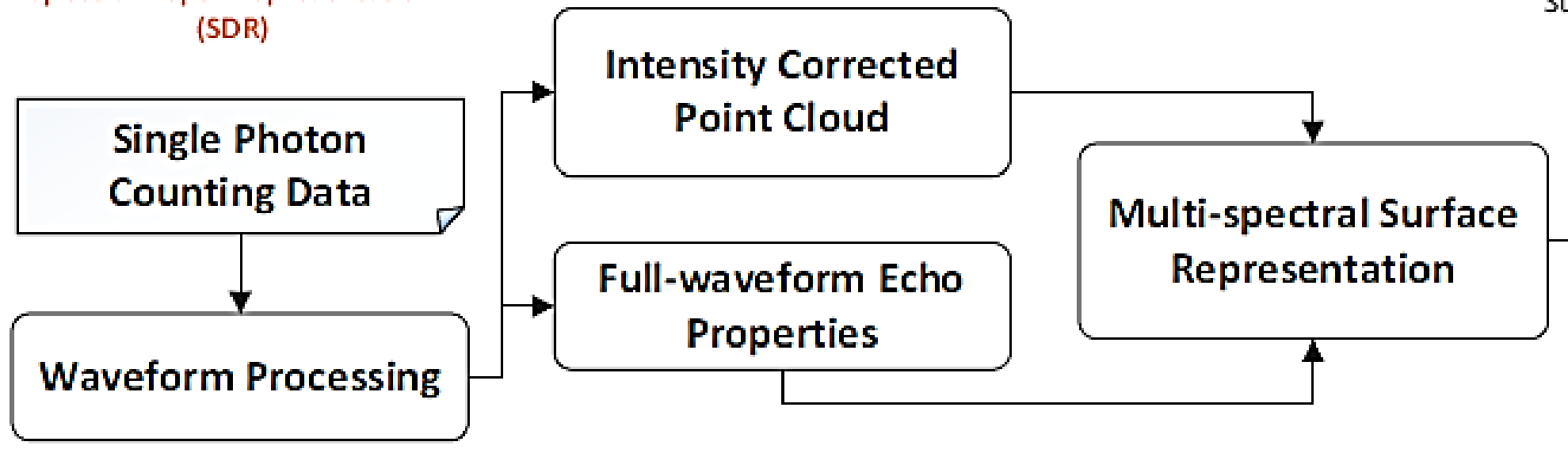
Methodology

- A novel reflectance aware surface representation, a **“Spectral Depth Representation (SDR)”** is proposed for underwater SPC and aerial LiDAR data.
-

Methodology

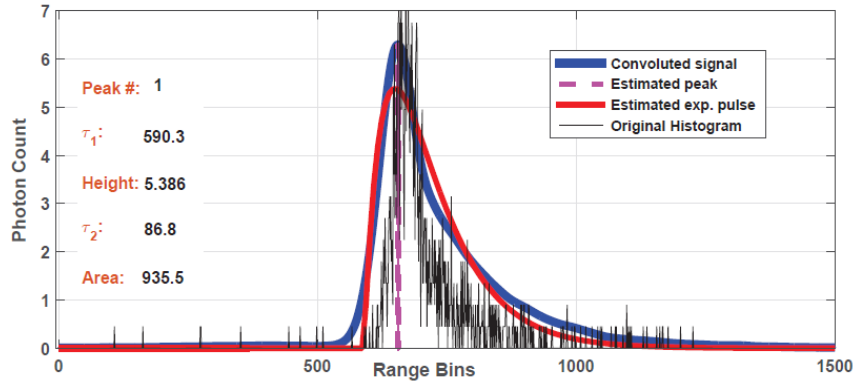
Spectral Depth Representation (SDR)

Stage 1



Stage 1: Spectral Depth Representation

Full-waveform Spectral Properties

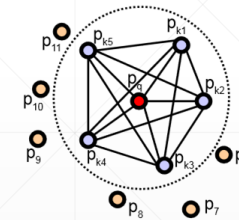
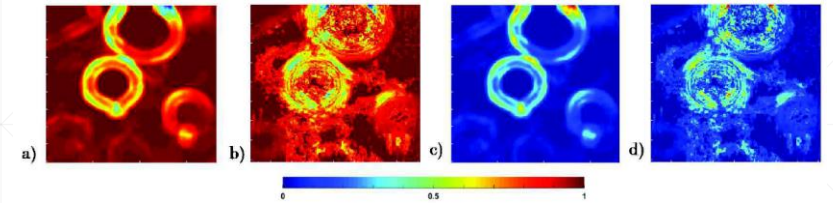
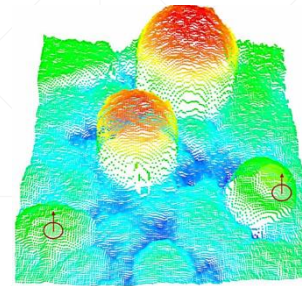


$$f(t) = k(e^{-t\mathcal{T}_1} - e^{-t\mathcal{T}_2}), \quad (t \geq 0),$$

where, $k = \frac{\mathcal{T}_2 e^{(t_p - t_0)\mathcal{T}_1}}{(\mathcal{T}_2 - \mathcal{T}_1)}$, and $t_p = \frac{\ln(\mathcal{T}_2/\mathcal{T}_1)}{(\mathcal{T}_2 - \mathcal{T}_1)}$

SPECTRAL DEPTH REPRESENTATION (SDR)

Depth Representation



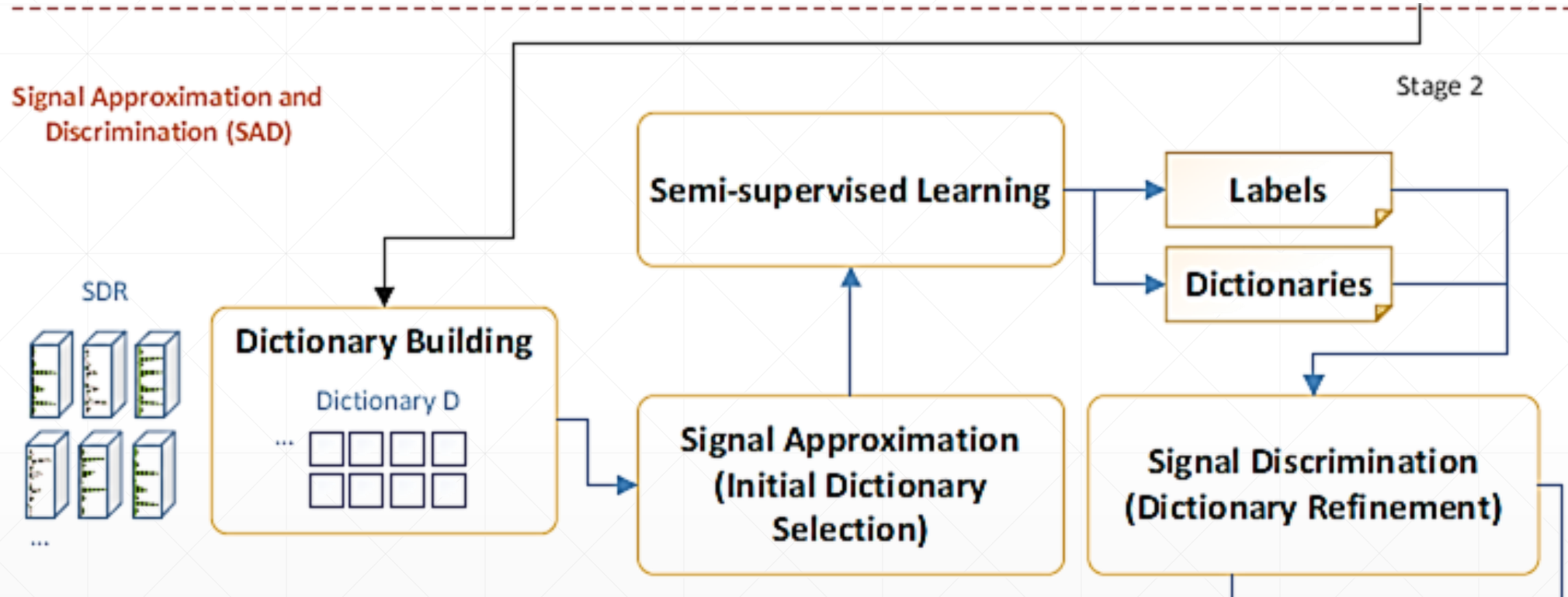
Linearity $L_{\mathcal{E}}$	$\frac{\mathcal{E}_1 - \mathcal{E}_2}{\mathcal{E}_1}$	Sphericity $S_{\mathcal{E}}$	$\frac{\mathcal{E}_3}{\mathcal{E}_1}$
Planarity $P_{\mathcal{E}}$	$\frac{\mathcal{E}_2 - \mathcal{E}_3}{\mathcal{E}_1}$	Anisotropy $A_{\mathcal{E}}$	$\frac{\mathcal{E}_1 - \mathcal{E}_3}{\mathcal{E}_1}$

$$F = \left[\left\{ \mathcal{T}_{1,\lambda} \right\}_{\lambda=1}^{\Lambda}, \left\{ \mathcal{T}_{2,\lambda} \right\}_{\lambda=1}^{\Lambda}, \left\{ A_{\lambda} \right\}_{\lambda=1}^{\Lambda}, A_{\mathcal{E}}, P_{\mathcal{E}}, S_{\mathcal{E}}, L_{\mathcal{E}}, D_z \right]$$

Stage 2.1: Signal Approximation & Discrimination

- **Discriminatory Sparse Codes are created** using a novel semi-supervised “**Signal Approximation and Discrimination (SAD)**” scheme.
-

Stage 2.1: Signal Approximation & Discrimination



$$\min_{\mathbf{Q}, \mathbf{Z}} \left[\beta_2 \sum_{n=1}^N \|f_n - q_n \mathbf{Z}\|^2 + \beta_1 \sum_{n=1}^N |q_n|_1 + G(\mathbf{Q}) \right],$$

subject to $|q_n| \leq 1, \forall n = 1, 2, \dots, N$

Stage 2.1a: Discriminant term $G(\mathbf{Q})$

Given: **Set of coefficients** $\mathbf{Q} = [q_1, q_2, \dots, q_K]$ Ω_c , for $1 \leq c \leq \Omega$ $\mu = \frac{1}{K} \sum_{k=1}^K q_k$

Class-wise mean $\mu_c = \frac{1}{K_c} \sum_{q \in \Omega_c} q$

Class-wise variance $v_c^2 = \frac{1}{K_c} \sum_{z \in \Omega_c} \|z - \mu_c\|_2^2$

$$G(\mathbf{Q}) = S_w^{-1} S_b$$

Inter-class scatter matrix $S_b = \left\| \sum_{c=1}^{\Omega} K_c (\mu_c - \mu) (\mu_c - \mu)^T \right\|_2^2$

Intra-class scatter matrix $S_w = \sum_{c=1}^{\Omega} v_c^2$

Stage 2.1b: Greedy Solution

Input: $\mathbf{F} = \{f_n\}_{n=1}^N \in \mathbb{R}^{N \times P}$, β_1, β_2

Output: Dictionary, atom indices and coefficients

$\mathbf{R}_0 \leftarrow \mathbf{F}$, $dictIdx \leftarrow \phi$

while $\mathbf{R}_0 \rightarrow 0$ **do**

$t \leftarrow 0$ Select $z_k \in \mathbf{Z}$, such that

$$\min_{\mathbf{Q}, \mathbf{Z}} \left[\beta_2 \sum_{n=1}^N \|f_n - q_n \mathbf{Z}\|^2 + \beta_1 \sum_{n=1}^N |q_n|_1 + G(\mathbf{Q}) \right],$$

subject to $|q_n| \leq 1, \forall n = 1, 2, \dots, N$

$dictIdx \leftarrow dictIdx \cup k$

// Projection and residual

$\mathbf{O}_t \leftarrow \mathbf{Q} * inv(\mathbf{Q}^T * \mathbf{Q}) * \mathbf{Q}^T$

$\mathbf{R}_t \leftarrow \mathbf{F} - \mathbf{O}_t \mathbf{F}$

$t \leftarrow t + 1$

end

return \mathbf{Q}, \mathbf{Z} , $dictIdx$

Recall...

Spectral Depth Representation (SDR)

$$\mathbf{F} = \left[\begin{array}{c} \{\mathcal{T}_{1,\lambda}\}_{\lambda=1}^{\Lambda}, \{\mathcal{T}_{2,\lambda}\}_{\lambda=1}^{\Lambda}, \{A_{\lambda}\}_{\lambda=1}^{\Lambda}, \\ A_{\mathcal{E}}, P_{\mathcal{E}}, S_{\mathcal{E}}, L_{\mathcal{E}}, D_z \end{array} \right]$$

Trying to solve...

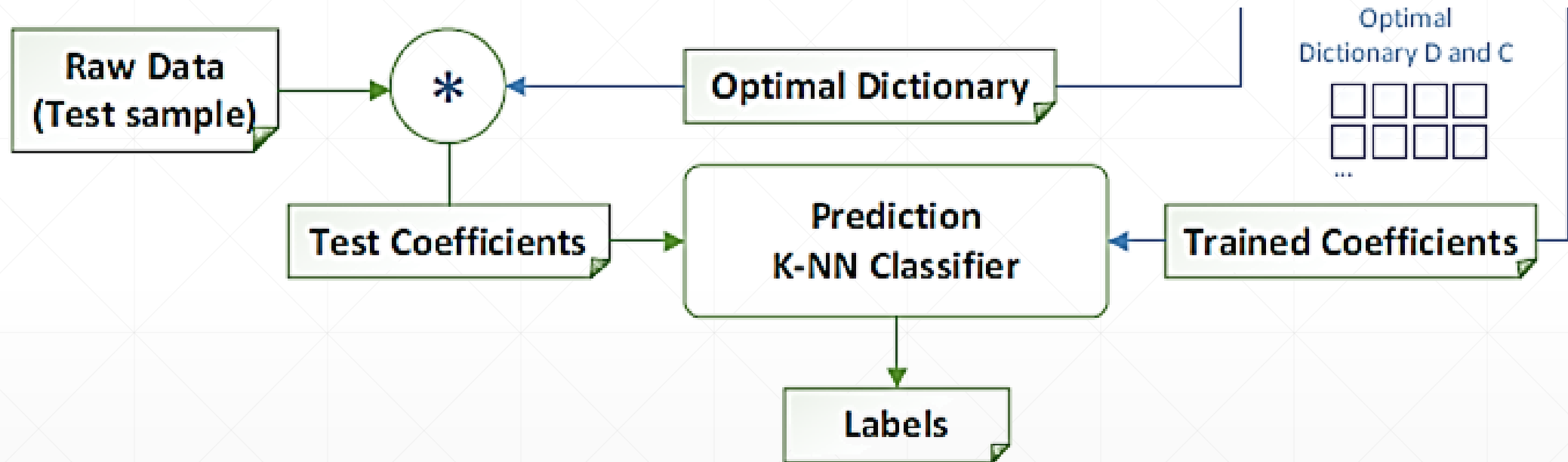
$$\min_{\mathbf{Q}, \mathbf{Z}} \left[\beta_2 \sum_{n=1}^N \|f_n - q_n \mathbf{Z}\|^2 + \beta_1 \sum_{n=1}^N |q_n|_1 + G(\mathbf{Q}) \right],$$

subject to $|q_n| \leq 1, \forall n = 1, 2, \dots, N$

Stage 3: Prediction

- **Signal labels** are generated using a classification scheme
-

Stage 3: Prediction



Summary...

Full-waveform + Shape Properties

Stage I (Algorithm 1 in the paper)



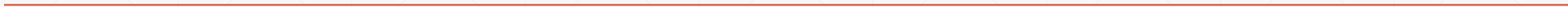
Sparse Spectral Depth Codes

Stage II (Algorithm 1 & 2 in the paper)



Pixel-wise Prediction

Stage III (Algorithm 1 in the paper)



Experiments

- **No. of samples:** 40,000 – 90,000
- **Signal dimension:** 53
- **No. of wavelengths:** 16 (500 – 725nm)
- **Laser repetition:** 19.5Mhz
- **Laser beam-diameter:** ~ 300 μ m
- **Environment:** Clear tap water
- **Target signature classification (pixel-wise)**
- **10 - fold cross-validation**
- **Compared against ground truth**

Experiment 1 – Material Discrimination



Sand



Plastic



Metal

Experiment 2 – Mine Discrimination



Sand



Plastic 1



Plastic 2



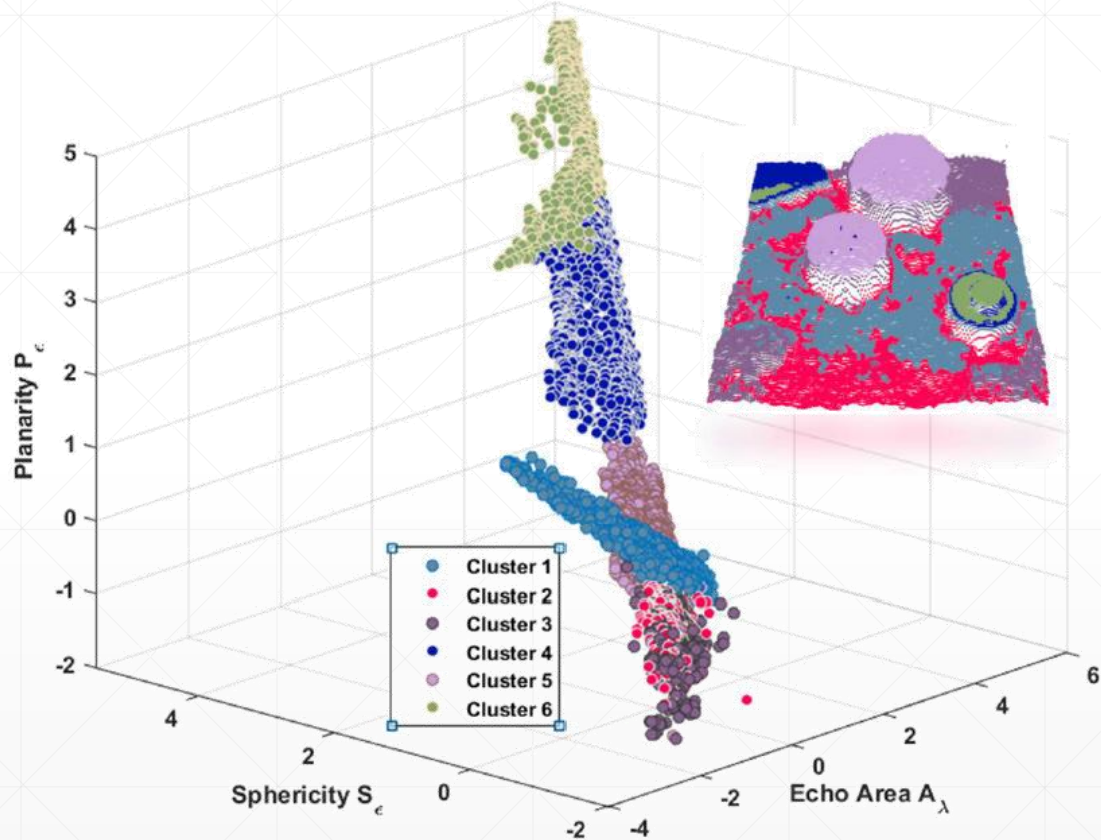
Metal 1



Metal 2

Experiment 3 – Without depth/curvature features

Results



Material Discrimination

	Sand	Plastic	Metal
Sand	0.9721	0.0144	0.0133
Plastic	0.0151	0.9823	0.0024
Metal	0.0140	0.0035	0.98239

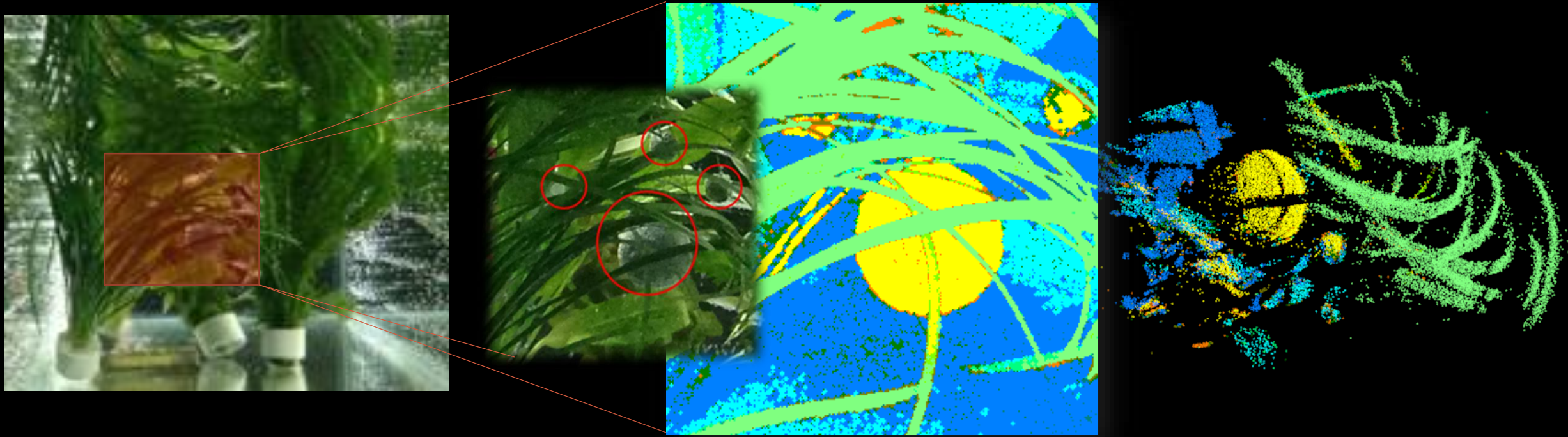
Mine Type Discrimination

	Plastic 1	Plastic 2	Metal 1	Metal 2	Sand
Plastic 1	0.9755	0	0.0020	0	0.0224
Plastic 2	0.0054	0.9905	0.0007	0.0020	0.0014
Metal 1	0.0014	0.0027	0.9946	0	0.0014
Metal 2	0.0014	0.0068	0	0.9891	0.0027
Sand	0.0102	0.0007	0	0.0007	0.9884

Effect of DR on accuracy

	Plastic 1	Plastic 2	Metal 1	Metal 2
Without DR(%)	92.65	95.65	97.62	98.10
With DR(%)	97.55	99.05	99.46	98.91

Underwater Foliage Penetration



- Preliminary results on floating mines
- Unsupervised clustering
- Performed only at **500nm**

Improvements



Future Work

- Greedy methods can be slow and do not scale for large real-world datasets... not anymore!
- How to handle non-linearity in the data?
- Different marine environments

More targets under investigation

- Different materials and background
- Floating targets behind foliage

A fast kernel discriminatory orthogonal dictionary learning method to classify large-scale, high-dimensional datasets and handle non-linearity.

Thank you!



University Defence Research Collaboration

For more information on the UDRC group
please visit: <http://www.mod-udrc.org>
