Bistatic Micro-Doppler Characteristics of Precession Targets

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Abstact: Micro-motion is one of the most important features for radar targ et recognition. Firstly, the bistatic micro-Doppler models corresponding to the bis tatic scattering centers of the precession targets are derived. Then, The dynamic simulation method of the bistatic echo of the precession target is presented usin g the bistatic scattering coefficients obtained via electromagnetic calculations, an d the bistatic scattering coefficients of the blunt-nosed biconical model are calcul ated using the multilevel fast multipole method. Finally, the theoretic analysis is v erified by comparing the time-frequency distribution of the bistatic echo sequenc es with the theoretical bistatic micro-Doppler. This research is helpful for utilizing the bistatic micro-Doppler for feature extraction and recognition of spatial micromotion targets.

1. Bistatic scattering Model

According to the geometrical diffraction theory, five bistatic scattering cen ters of the blunt-nosed biconical model are located at the intersection of t he vertex, cone-cylinder edge and bottom edge and the plane that is const

3. Dynamic simulation and analysis

A conductive blunt-nosed biconical model is constructed using FEKO s oftware to verify the previously described analysis using the parameter s shown in Fig.2. And the electromagnetic calculation parameters are lis ted in Table 1.

Parameter	Unit	Value
Frequency	GHz	8
Incident elevation	deg	0~180
Scattering elevation	deg	0~180
Scattering azimuth	deg	0~180
Angle interval	deg	0.2

Table.1 Electromagnetic calculation parameters

The dynamic simulation flow chart is described as follows

ructed by the symmetry axis and the bisector of the bistatic angle, and the y are labeled as A,B,C,D,E. These bistatic scattering centers changes with the target moving and bistatic geometric configuration. Especially, for the fixed bistatic radar, these bistatic scattering centers will slide on the edge continuously with the target precession.





Fig.1 Precession blunt-nosed biconical model

Fig.2 Target size

The angle between the incident vector and the symmetry axis can be ex pressed as

 $\cos\theta_i = \cos\theta\cos\alpha_i + \sin\theta\sin\alpha_i\cos(\omega t + \phi_0)$

The angle between the scattering vector and the symmetry axis can be expressed as

 $\cos\theta_{\rm s} = \cos\theta\cos\alpha_{\rm s} + \sin\theta\sin\alpha_{\rm s}\cos\left(\omega t + \phi_0 - \beta_{\rm s}\right)$

The bistatic angle satisfies

 $\cos(\psi) = \sin \alpha_i \sin \alpha_s \cos(\beta_i - \beta_s) + \cos \alpha_i \cos \alpha_s$

According to the spatial geometry, the azimuth angle of the LOS of



Fig.3 Flow chart of the dynamic simulation

The simulation parameters: precession angle 10deg and precession n frequency 0.5Hz.



the receiver in the local ordinates, can be approximated by the following expression

 $\cos\varphi_{\rm s} \approx \frac{\cos\psi - \cos\theta_{\rm i}\cos\theta_{\rm s}}{\sin\theta_{\rm i}\sin\theta_{\rm s}}$

The bistatic scattering coefficients are decided by the angles

 $\left(\theta_{\mathrm{i}},\,\theta_{\mathrm{s}},\,\varphi_{\mathrm{s}}\right)$

2. Bistatic micro-Doppler Model

According to the bistatic range and differential, the bistatic micro-Doppler of the scattering center A, B,C D and E can be expressed as follows, respectively.

$$\begin{cases} f_{A,C}(t) = -2\frac{f_0}{c}\omega\cos\frac{\psi}{2}\sin\theta\sin\alpha\sin\left(\omega t + \phi_0 - \phi_1\right)\left(-|OO_1|\pm r_1\Delta(t)/\sqrt{1-\Delta^2(t)}\right) \\ f_{B,D}(t) = \frac{2f_0}{c}\omega\cos\frac{\psi}{2}\sin\alpha\sin\theta\cos\left(\omega t + \phi_0 - \phi_1\right)\left(-|OO_2|\mp r_2\Delta(t)/\sqrt{1-\Delta^2(t)}\right) \\ f_E(t) = -2|OO_3|\frac{f_0}{c}\omega\cos\frac{\psi}{2}\sin\alpha\sin\theta\sin\left(\omega t + \phi_0 - \phi_1\right) \end{cases}$$



Fig.4 Time-frequency distribution of precession blunt-nosed biconical model

4.Conclusion

Although the bistatic micro-Doppler model can be simplified as the monosta tic case, the complexity of bistatic geometry configurations leads to large dif ferences in observed target characteristics, which bring new challenges in u tilizing the bistatic micro-Doppler for feature extraction and recognition. Onl y part of the scattering centers can be observed with one observation aspec t from the dynamic simulation, whereas the entirety of all scattering centers can be observed by multi-aspect observation. Future studies will consider a method for simultaneous extraction of the target size and precession angle via multiple receivers.